Pume Tuchinda

EDUCATION

B.S. Computer Engineering, Purdue University, West Lafayette, IN

08/2019 - 12/2022

Focus: Computer Vision and Machine Learning

Professional Experience

Vidyasirimedhi Institute of Science and Technology (vistec).....

RESEARCH ASSISTANT - NATURAL LANGUAGE AND REPRESENTATION LEARNING LAB

08/2024 - Present

- Multilingual Reasoning [1]: Investigated multilingual reasoning in large language models via program-of-thought (PoT) prompting; ACL Findings 2025
- Datasets [2]: Developed a Thai cultural benchmark and instruction-tuned dataset to evaluate and improve large language models' understanding of Thai culture; EMNLP Main 2025
- Vision Language Model:
 - Optimizing vision-language model efficiency using knowledge distillation techniques; targeting submission to WACV 2025
 - Collaborating with SEACrowd to develop and evaluate multilingual vision language models tailored for Southeast Asian languages and cultural contexts.
- Open Source Software: Maintaining the WangchanX Finetune Toolkit and training Thai large language models for public release under the WangchanX project.

AI and Robotics Ventures.....

Data Scientist

06/2022 - 07/2024

- Fine-tuned YOLOv8 for signboard detection, achieving 85.20% mAP@50 on a diverse dataset of over 50,000 images, and deployed onto AWS Batch and SageMaker for nationwide inference, boosting detection accuracy by 25% over the baseline model across 100+ locations.
- Integrated and deployed Llava for land-use classification and change detection on satellite and drone imagery which significantly increased the efficiency of each municipality.
- Developed an automated image labelling pipeline for object detection and segmentation, increasing the labelling efficiency by 1.5x and accelerating development time for new use-cases by 2x.

Purdue University

RESEARCH ASSISTANT - IMAGE PROCESSING AND ANALYSIS LAB

08/2021 - 12/2022

- Led a team of 6 students on researching the perception system for self-driving cars to perform traffic object detection, lane intance segmentation, and drivable area segmentation within a unified model, under the supervision of Dr. Edward Delp and Dr. Carla Zoltowski.
- Doubled the frame rate of multi-task networks from 30 to 60 FPS while maintaining state-of-the-art accuracy with 69.8% mIOU for traffic object detection and 84.76% mIOU for lane and drivable area segmentation on the BDD100K Dataset.
- Explored self-supervised monocular depth estimation to extend YOLOv5 to be able to perform depth estimation from a single image and map out the distances of each object in the image.

Research Assistant - Cam2 Lab

01/2021 - 07/2021

• Optimized YOLOv5 for ball and person detections using Quantization Aware Training and pruning methods to receive an increase in computation time by 30-40% while sacrificing at most 5% accuracy.

• Developed an image stitching algorithm to stitch a single or dual field of view image taken by a Solar Sail to create a a 360° panoramic image of the sail for generating a 3D model used in image analysis.

Publications

*: Equal Contribution

[1] Wangchan Thai Instruct: An instruction-following Dataset for Culture-Aware, Multitask, and Multidomain Evaluation in Thai

Peerat Limkonchotiwat*, **Pume Tuchinda***, Lalita Lowphansirikul, Surapon Nonesung, Panuthep Tasawong, Alham Fikri Aji, Can Udomcharoenchaikit, Sarana Nutanong

Proceedings of the 2025 Conference on Empirical Methods in Natural Language Processing

[2] Towards Better Understanding of Program-of-Thought Reasoning in Cross-Lingual and Multilingual Environments

Patomporn Payoungkhamdee, Pume Tuchinda, Jinheon Baek, Samuel Cahyawijaya, Can Udomcharoenchaikit, Potsawee Manakul, Peerat Limkonchotiwat, Ekapol Chuangsuwanich, Sarana Nutanong Findings of the Association for Computational Linguistics, 2025

SKILL

Languages: English (Native), Thai (Native), Japanese (Limited Working Proficiency)
Programming Languages: Python, SQL, C++, C, MATLAB
Frameworks & Libraries: PyTorch, JaX, Transformers, vLLM, Scikit-learn

Tools & Platforms: Docker, AWS (EC2, S3, Batch, Sagemaker)